EE382N (20): Computer Architecture - Parallelism and Locality Fall 2011

#### Lecture 11 – Parallelism in Software II

Mattan Erez



The University of Texas at Austin

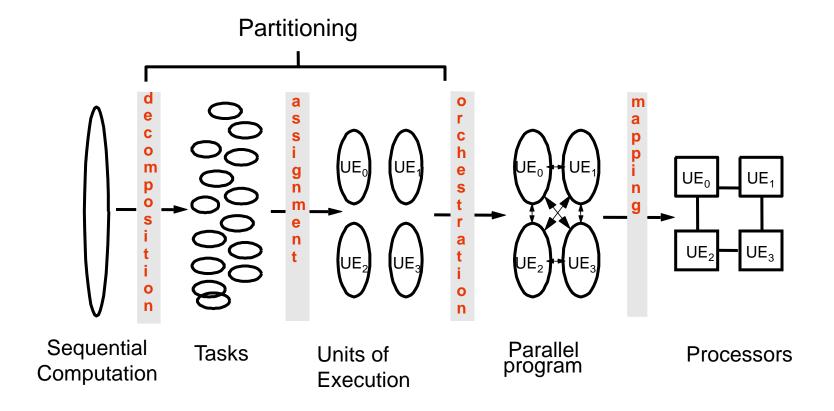


#### **Credits**

- Most of the slides courtesy Dr. Rodric Rabbah (IBM)
  - Taken from 6.189 IAP taught at MIT in 2007.



# 4 Common Steps to Creating a Parallel Program





## **Decomposition**

- Identify concurrency and decide at what level to exploit it
- Break up computation into tasks to be divided among processes
  - Tasks may become available dynamically
  - Number of tasks may vary with time
- Enough tasks to keep processors busy
  - Number of tasks available at a time is upper bound on achievable speedup

# **Assignment**

- Specify mechanism to divide work among PEs
  - Balance work and reduce communication
- Structured approaches usually work well
  - Code inspection or understanding of application
  - Well-known design patterns
- As programmers, we worry about partitioning first
  - Independent of architecture or programming model?
  - Complexity often affects decisions
  - Architectural model affects decisions

# Orchestration and Mapping

- Computation and communication concurrency
- Preserve locality of data
- Schedule tasks to satisfy dependences early
- Survey available mechanisms on target system

# Main considerations: locality, parallelism, mechanisms (efficiency and dangers)

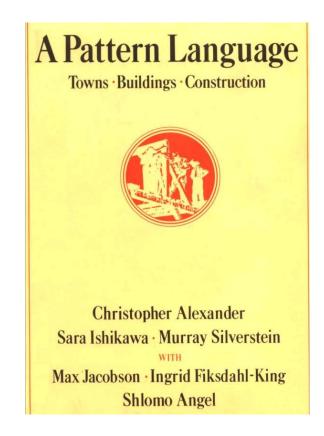
# Parallel Programming by Pattern

- Provides a cookbook to systematically guide programmers
  - Decompose, Assign, Orchestrate, Map
  - Can lead to high quality solutions in some domains
- Provide common vocabulary to the programming community
  - Each pattern has a name, providing a vocabulary for discussing solutions
- Helps with software reusability, malleability, and modularity
  - Written in prescribed format to allow the reader to quickly understand the solution and its context
- Otherwise, too difficult for programmers, and software will not fully exploit parallel hardware



# **History**

- Berkeley architecture professor
  Christopher Alexander
- In 1977, patterns for city planning, landscaping, and architecture in an attempt to capture principles for "living" design

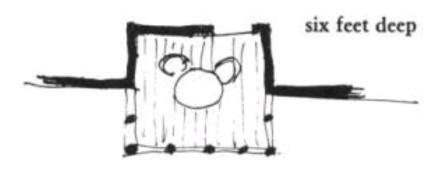




# Example 167 (p. 783): 6ft Balcony

#### Therefore:

Whenever you build a balcony, a porch, a gallery, or a terrace always make it at least six feet deep. If possible, recess at least a part of it into the building so that it is not cantilevered out and separated from the building by a simple line, and enclose it partially.





# ADDISON-WESLEY PROFESSIONAL COMPUTING SERIES

# Patterns in Object-Oriented Programming

- Design Patterns: Elements of Reusable Object-Oriented Software (1995)
  - Gang of Four (GOF): Gamma, Helm, Johnson, Vlissides
  - Catalogue of patterns
  - Creation, structural, behavioral



Elements of Reusable Object-Oriented Software

Erich Gamma Richard Helm Ralph Johnson John Vlissides



Foreword by Grady Booch



# Patterns for Parallelizing Programs

# 4 Design Spaces

#### **Algorithm Expression**

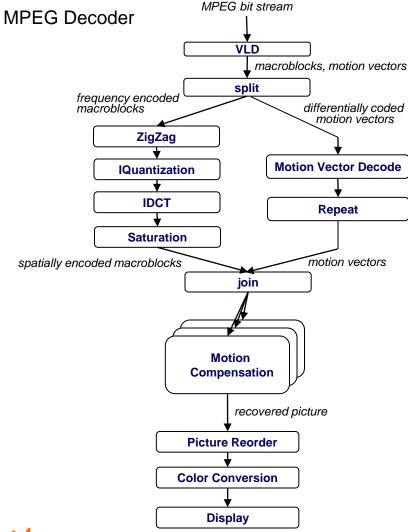
- Finding Concurrency
  - Expose concurrent tasks
- Algorithm Structure
  - Map tasks to processes to exploit parallel architecture

#### **Software Construction**

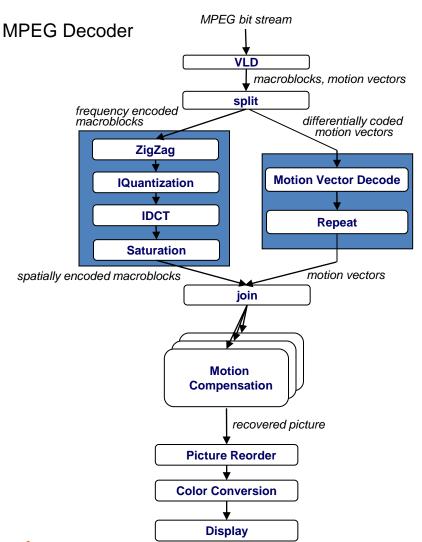
- Supporting Structures
  - Code and data structuring patterns
- Implementation
  Mechanisms
  - Low level mechanisms used to write parallel programs

Patterns for Parallel Programming. Mattson, Sanders, and Massingill (2005).



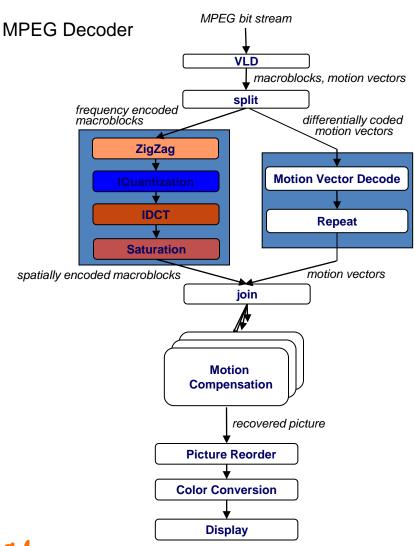




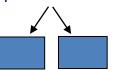


- Task decomposition
  - Independent coarse-grained computation
  - Inherent to algorithm
- Sequence of statements (instructions) that operate together as a group
  - Corresponds to some logical part of program
  - Usually follows from the way programmer thinks about a problem

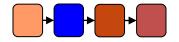




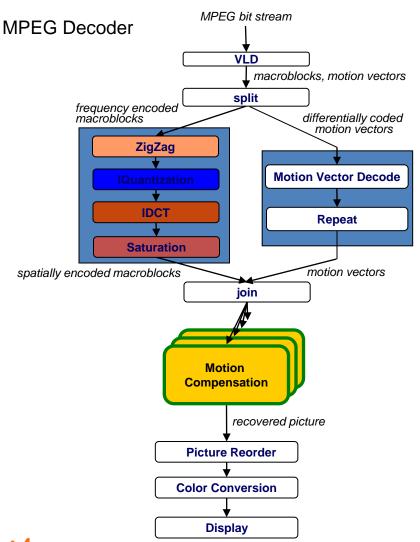
- Task decomposition
  - Parallelism in the application



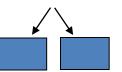
- Pipeline task decomposition
  - Data assembly lines
  - Producer-consumer chains



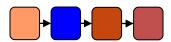




- Task decomposition
  - Parallelism in the application



- Pipeline task decomposition
  - Data assembly lines
  - Producer-consumer chains



- Data decomposition
  - Same computation is applied to small data chunks derived from large data set



# **Guidelines for Task Decomposition**

- Algorithms start with a good understanding of the problem being solved
- Programs often naturally decompose into tasks
  - Two common decompositions are
    - Function calls and
    - Distinct loop iterations
- Easier to start with many tasks and later fuse them,
  rather than too few tasks and later try to split them



# **Guidelines for Task Decomposition**

#### Flexibility

- Program design should afford flexibility in the number and size of tasks generated
  - Tasks should not tied to a specific architecture
  - Fixed tasks vs. Parameterized tasks

#### Efficiency

- Tasks should have enough work to amortize the cost of creating and managing them
- Tasks should be sufficiently independent so that managing dependencies doesn't become the bottleneck

#### Simplicity

 The code has to remain readable and easy to understand, and debug

# Case for Pipeline Decomposition

- Data is flowing through a sequence of stages
  - Assembly line is a good analogy



- What's a prime example of pipeline decomposition in computer architecture?
  - Instruction pipeline in modern CPUs
- What's an example pipeline you may use in your UNIX shell?
  - Pipes in UNIX: cat foobar.c | grep bar | wc
- Other examples
  - Signal processing
  - Graphics



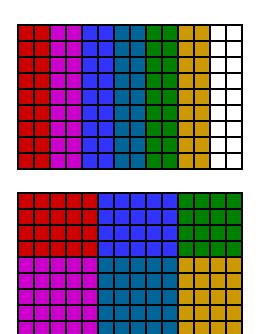
# **Guidelines for Data Decomposition**

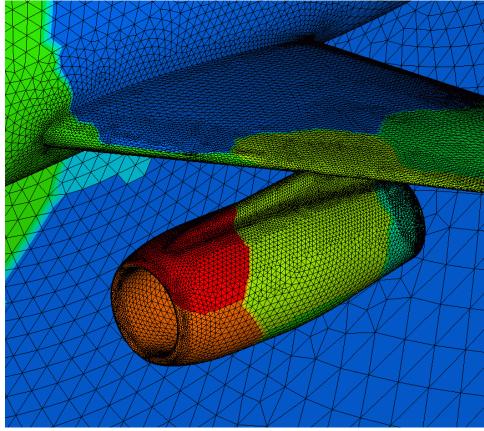
- Data decomposition is often implied by task decomposition
- Programmers need to address task and data decomposition to create a parallel program
  - Which decomposition to start with?
- Data decomposition is a good starting point when
  - Main computation is organized around manipulation of a large data structure
  - Similar operations are applied to different parts of the data structure



# **Common Data Decompositions**

- Geometric data structures
  - Decomposition of arrays along rows, columns, blocks
  - Decomposition of meshes into domains

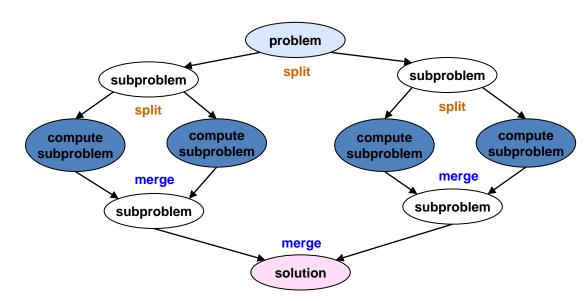






# **Common Data Decompositions**

- Geometric data structures
  - Decomposition of arrays along rows, columns, blocks
  - Decomposition of meshes into domains
- Recursive data structures
  - Example: decomposition of trees into sub-trees





# **Guidelines for Data Decomposition**

#### Flexibility

 Size and number of data chunks should support a wide range of executions

#### Efficiency

 Data chunks should generate comparable amounts of work (for load balancing)

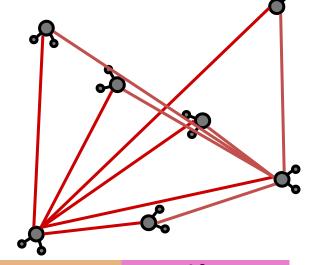
#### Simplicity

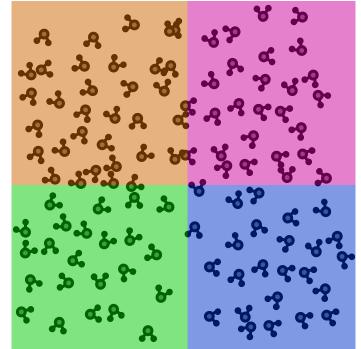
 Complex data compositions can get difficult to manage and debug



# **Data Decomposition Examples**

- Molecular dynamics
  - Compute forces
  - Update accelerations and velocities
  - Update positions
- Decomposition
  - Baseline algorithm is N<sup>2</sup>
    - All-to-all communication
  - Best decomposition is to treat mols. as a set
  - Some advantages to geometric discussed in future lecture

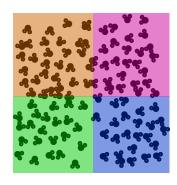




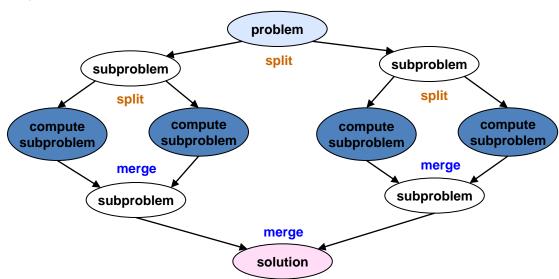


# **Data Decomposition Examples**

- Molecular dynamics
  - Geometric decomposition



- Merge sort
  - Recursive decomposition





# **Dependence Analysis**

 Given two tasks how to determine if they can safely run in parallel?

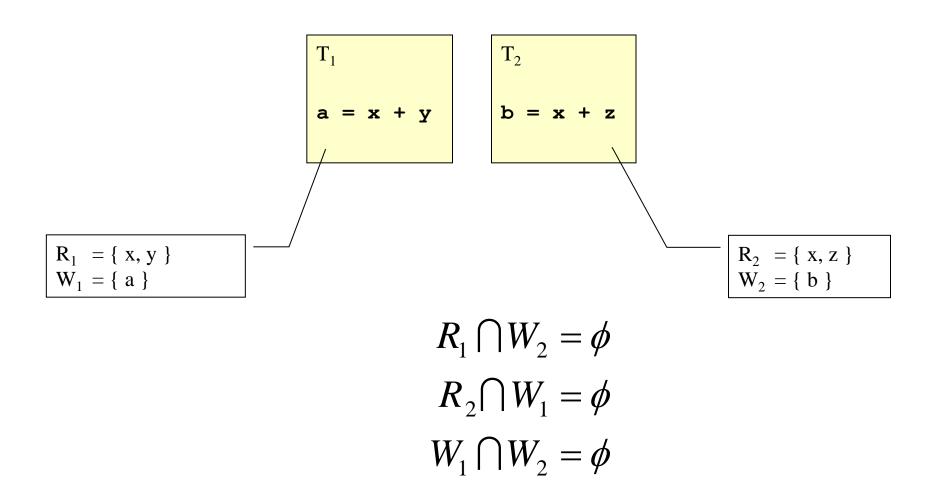


#### Bernstein's Condition

- $R_i$ : set of memory locations read (input) by task  $T_i$
- $W_j$ : set of memory locations written (output) by task  $T_j$
- Two tasks  $T_1$  and  $T_2$  are parallel if
  - input to  $T_1$  is not part of output from  $T_2$
  - input to  $T_2$  is not part of output from  $T_1$
  - outputs from  $T_1$  and  $T_2$  do not overlap



### Example





# Patterns for Parallelizing Programs

# 4 Design Spaces

#### **Algorithm Expression**

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#### **Software Construction**

- Supporting Structures
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Patterns for Parallel Programming. Mattson, Sanders, and Massingill (2005).



# Algorithm Structure Design Space

- Given a collection of concurrent tasks, what's the next step?
- Map tasks to units of execution (e.g., threads)
- Important considerations
  - Magnitude of number of execution units platform will support
  - Cost of sharing information among execution units
  - Avoid tendency to over constrain the implementation
    - Work well on the intended platform
    - Flexible enough to easily adapt to different architectures



# **Major Organizing Principle**

 How to determine the algorithm structure that represents the mapping of tasks to units of execution?

- Concurrency usually implies major organizing principle
  - Organize by tasks
  - Organize by data decomposition
  - Organize by flow of data



# Organize by Tasks?

